Mohamed Ahmed Abdelmotaleb Shoaib 18P6395

18p6395@eng.asu.edu.eg

MCT 331 Midterm submission

Assembly Module

A picture containing logo

Description automatically generated

Contents

[Abstract: - 3 -](#_Toc87958823)

[Introduction: - 3 -](#_Toc87958824)

[1. The Cad: - 4 -](#_Toc87958825)

[2. The Matlab: - 6 -](#_Toc87958826)

[3. The Simulink Circuit: - 7 -](#_Toc87958827)

[4. The Contacts: - 8 -](#_Toc87958828)

[5. The Signals: - 11 -](#_Toc87958829)

# Abstract:

Diagram

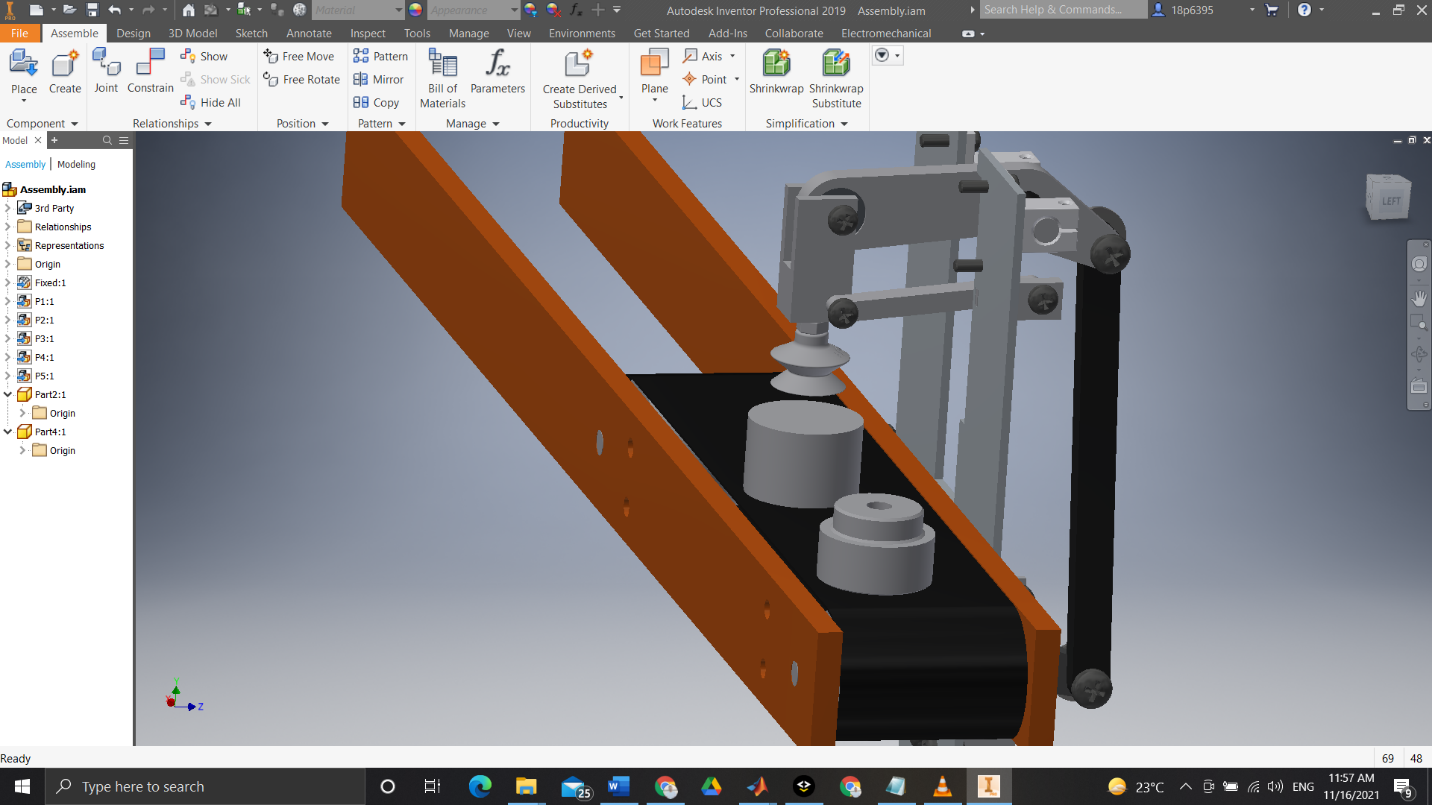
Description automatically generated with medium confidenceBy talking about complex systems, systems engineering is always named as the only  
way out for the enhancement of system understanding and the reduction of system  
complexity in the design process. After an identification of the essential aspects and  
concepts for pursuing systems engineering. A standardization for the development process  
of the mechatronics system is VDI 2206.

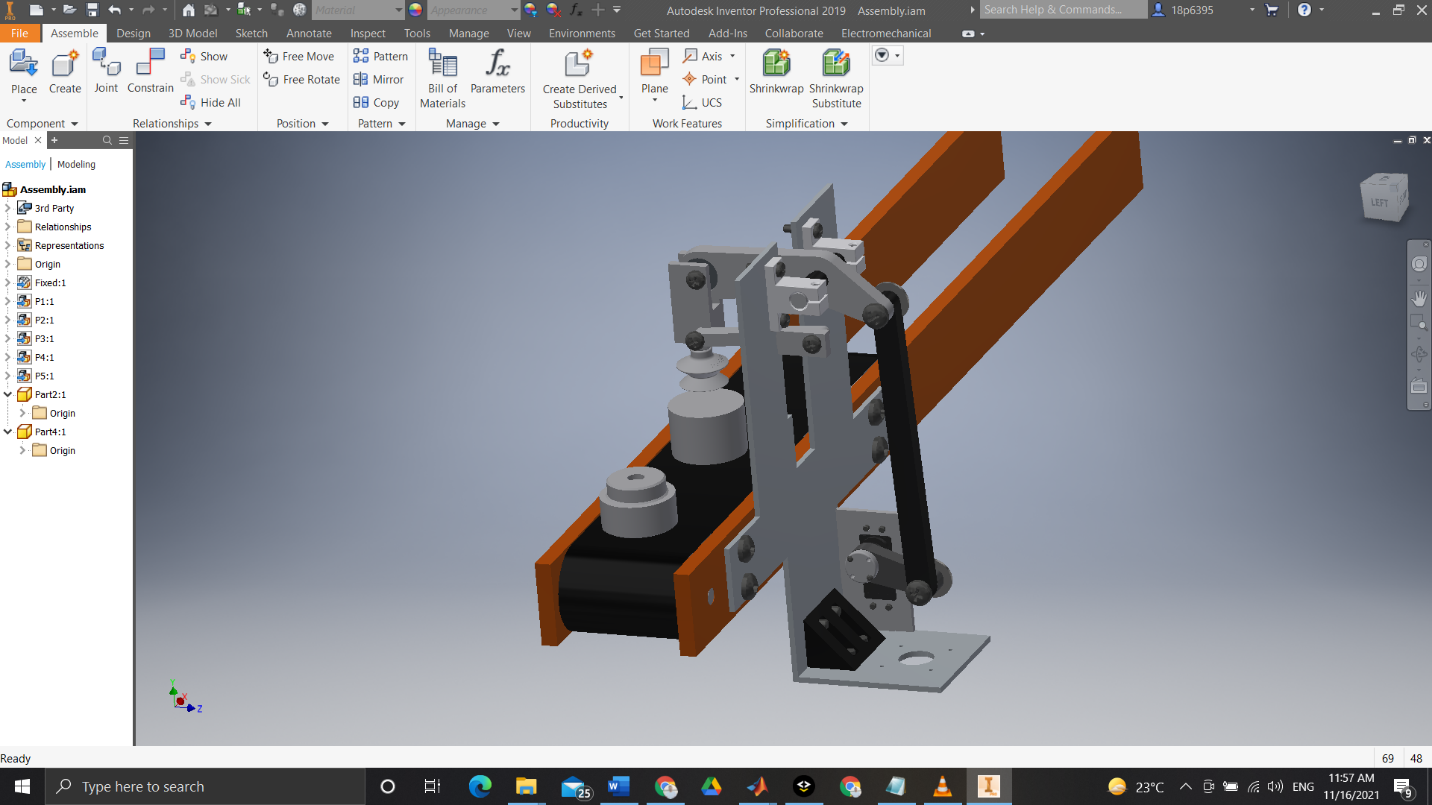
The main purpose of matlab simulation to try to make the system working and reliable without making a prototype of the project and cost money in real big project. The matlab helped us to see each module working.

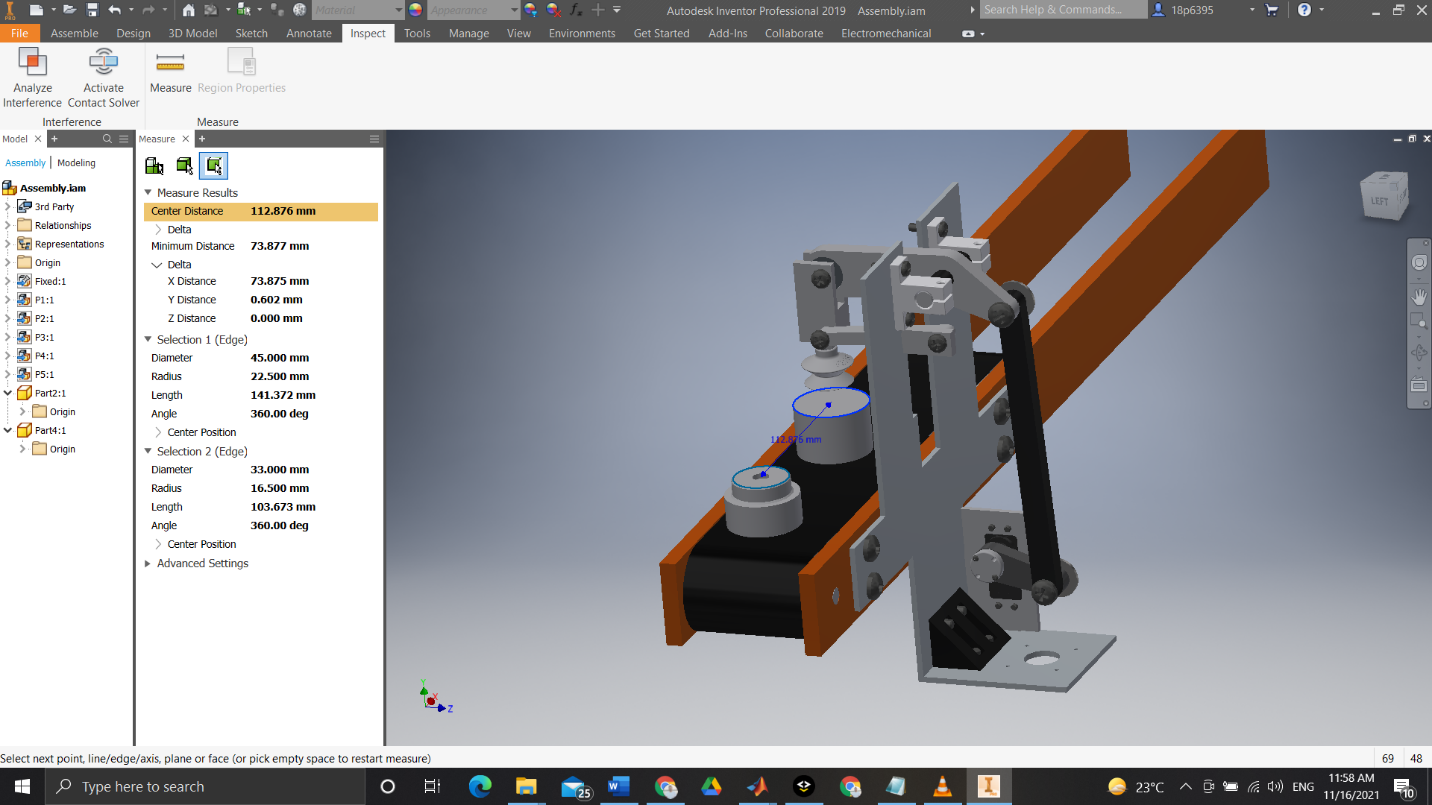
# Introduction:

The assembly module is responsible to put the 2 parts on each other. I used 2 four mechanism, the first one is moving the suction cup up and down, the second one is to fix the suction cup holder in its position so we can press the suction cup.

# The Cad:



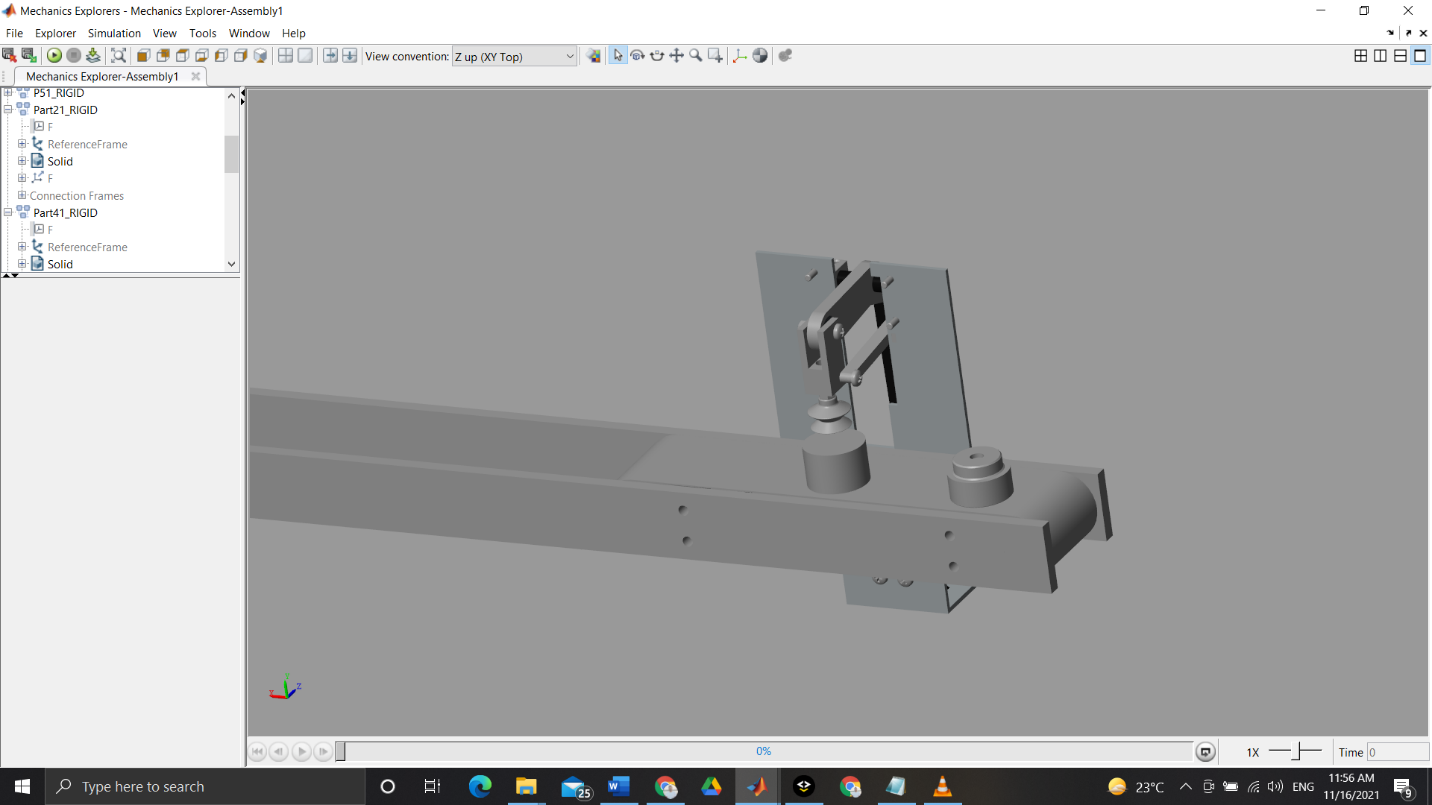






The distance between the 2 parts is about 113 mm will be used in the matlab, and the are concentric with the suction cup.

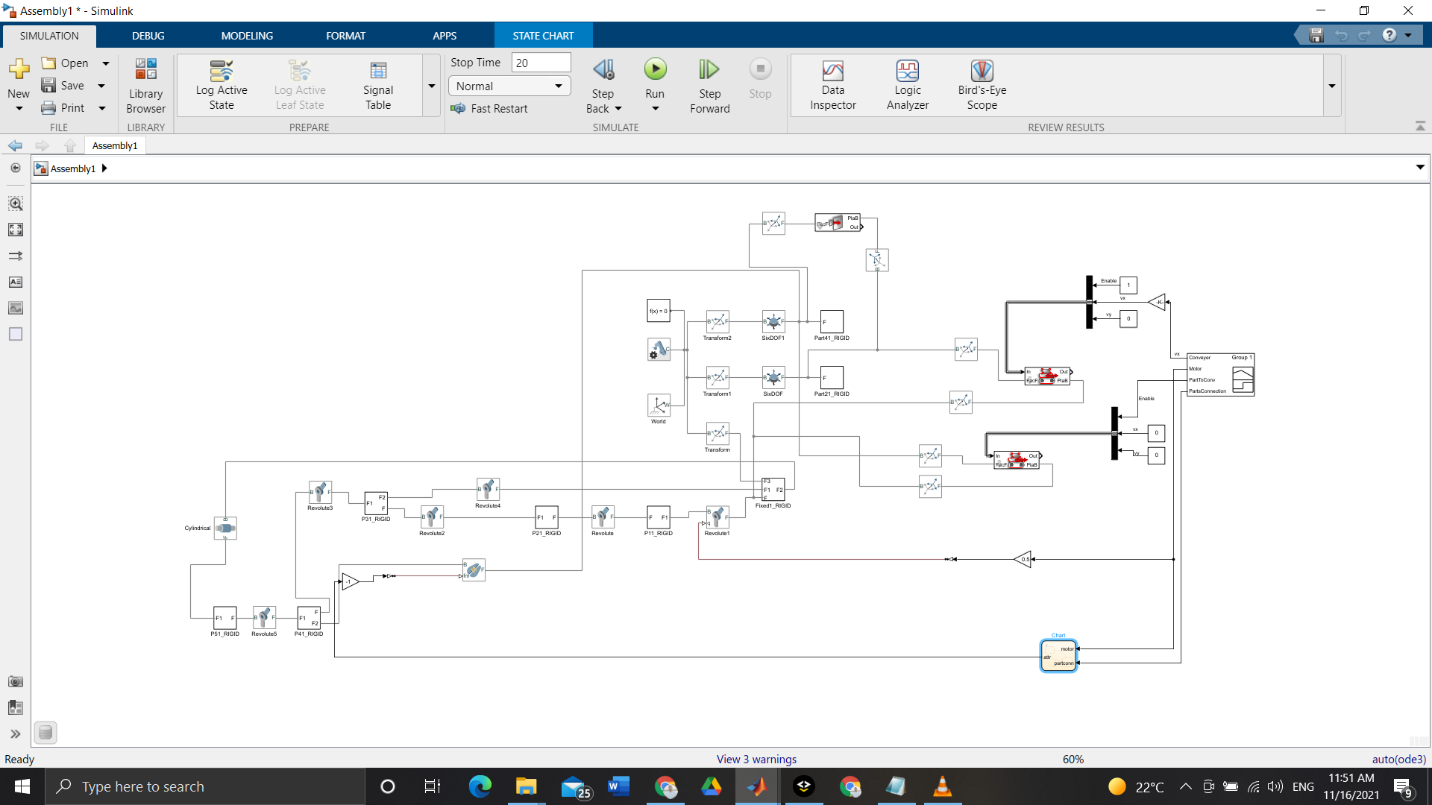
# The Matlab:



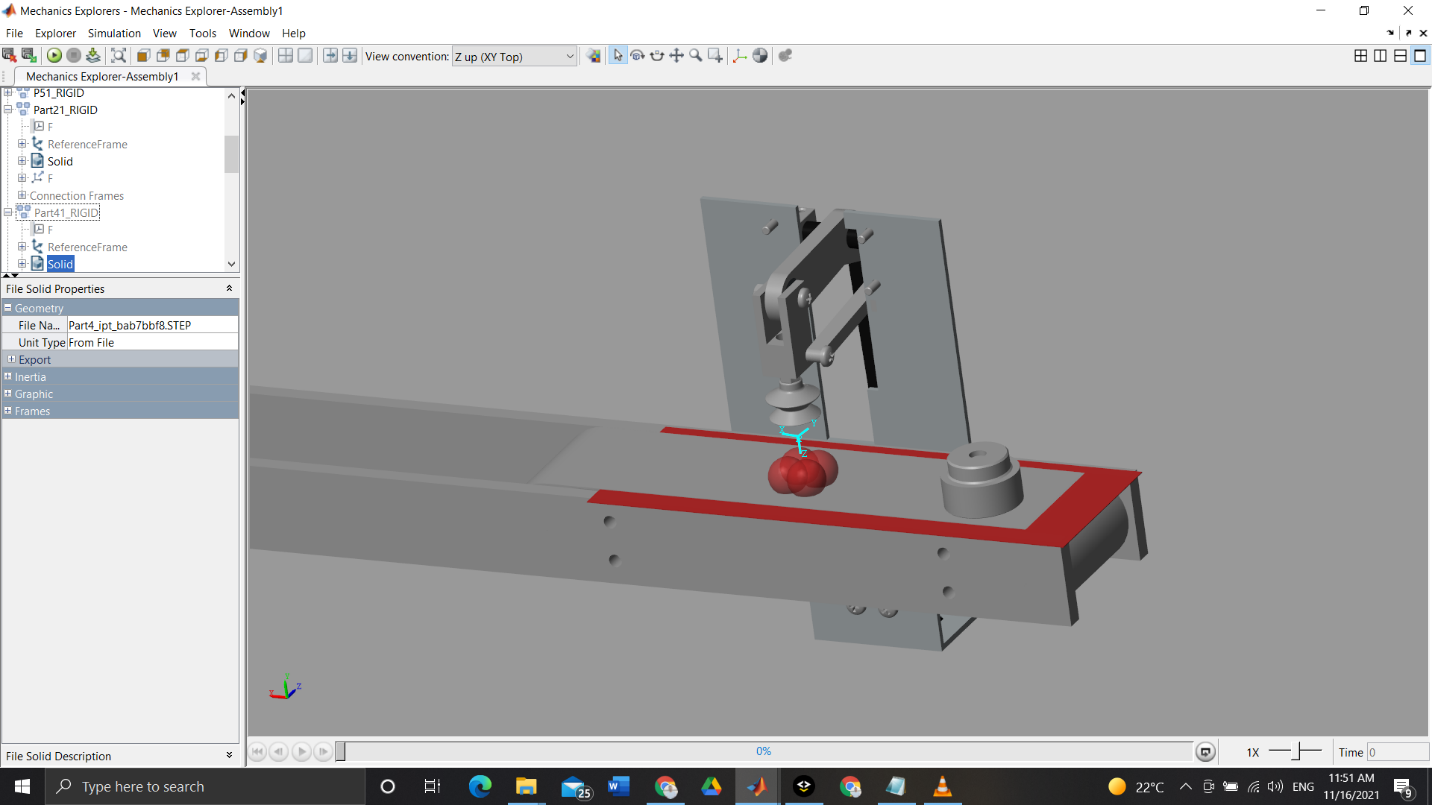
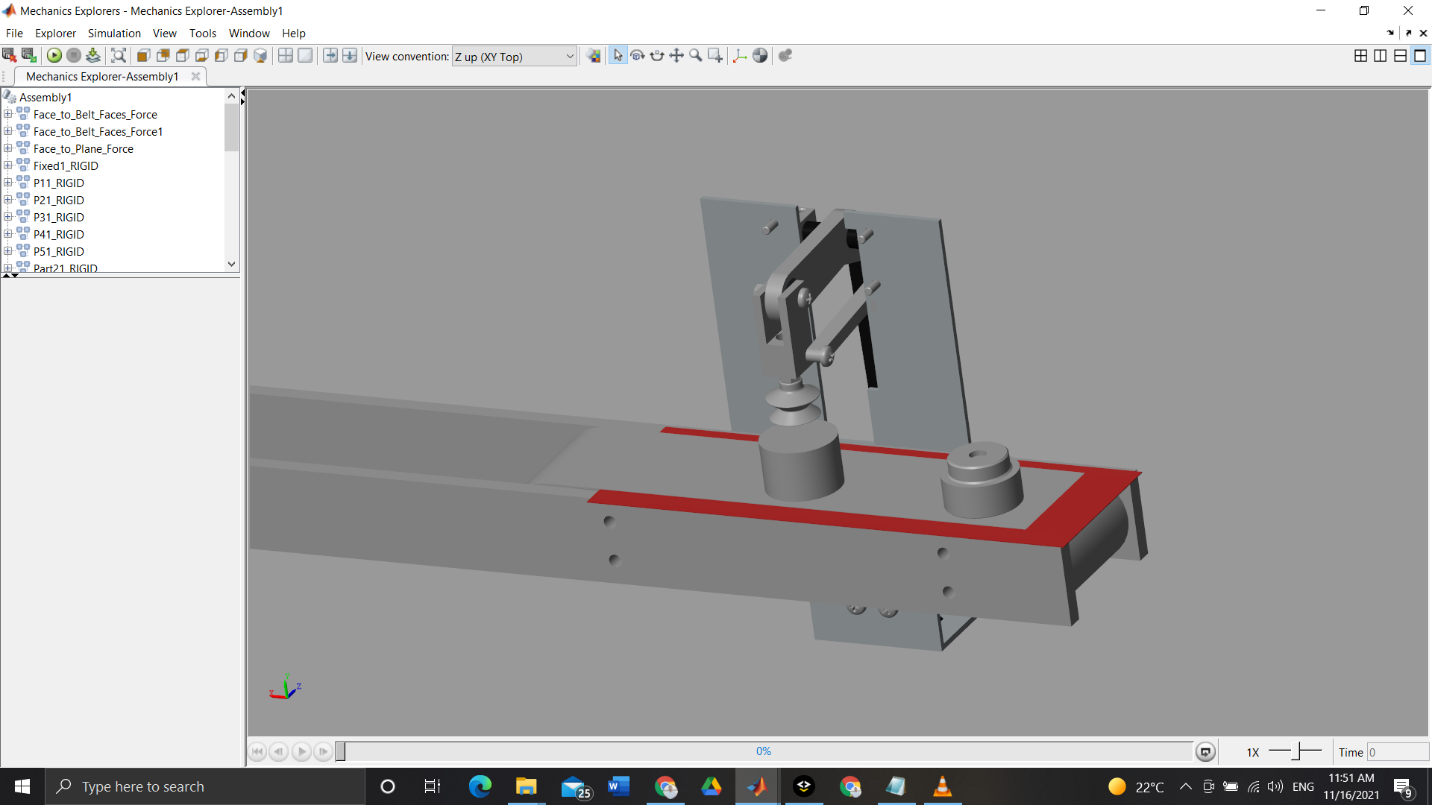
Video for the whole module working:

<https://drive.google.com/file/d/1HVslpROE1Dep3GdlN3tZtgvX7XqWqQHC/view?usp=sharing>

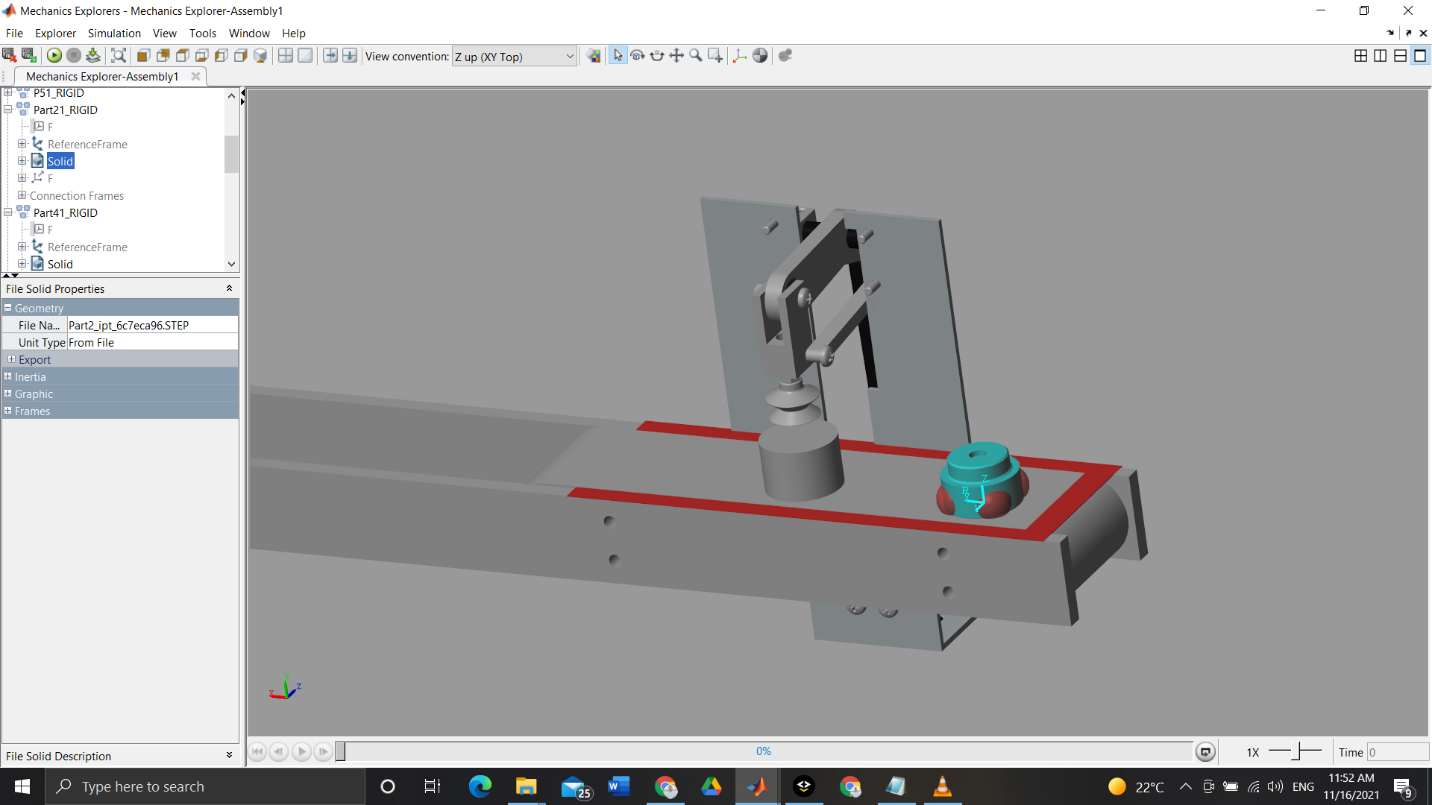
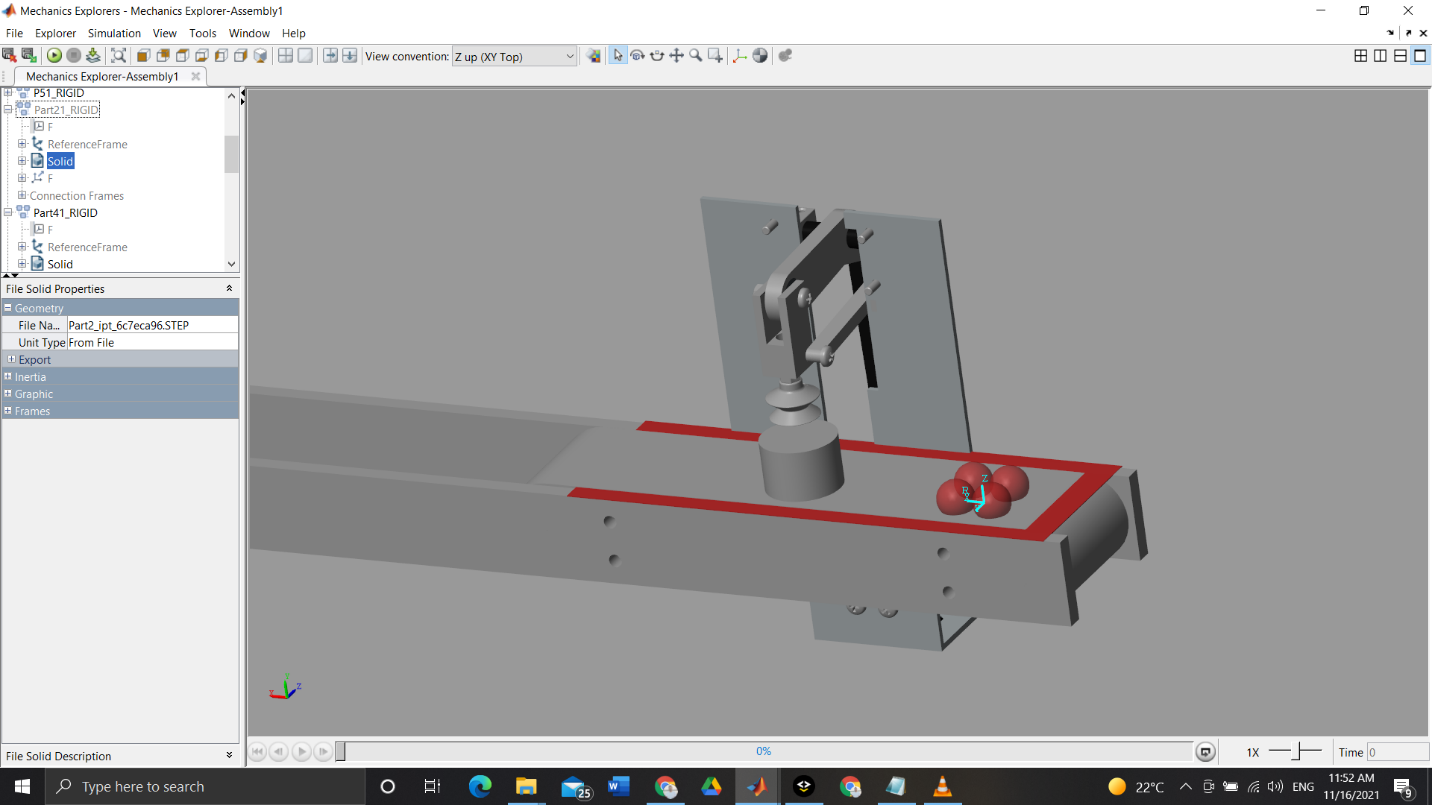
# The Simulink Circuit:



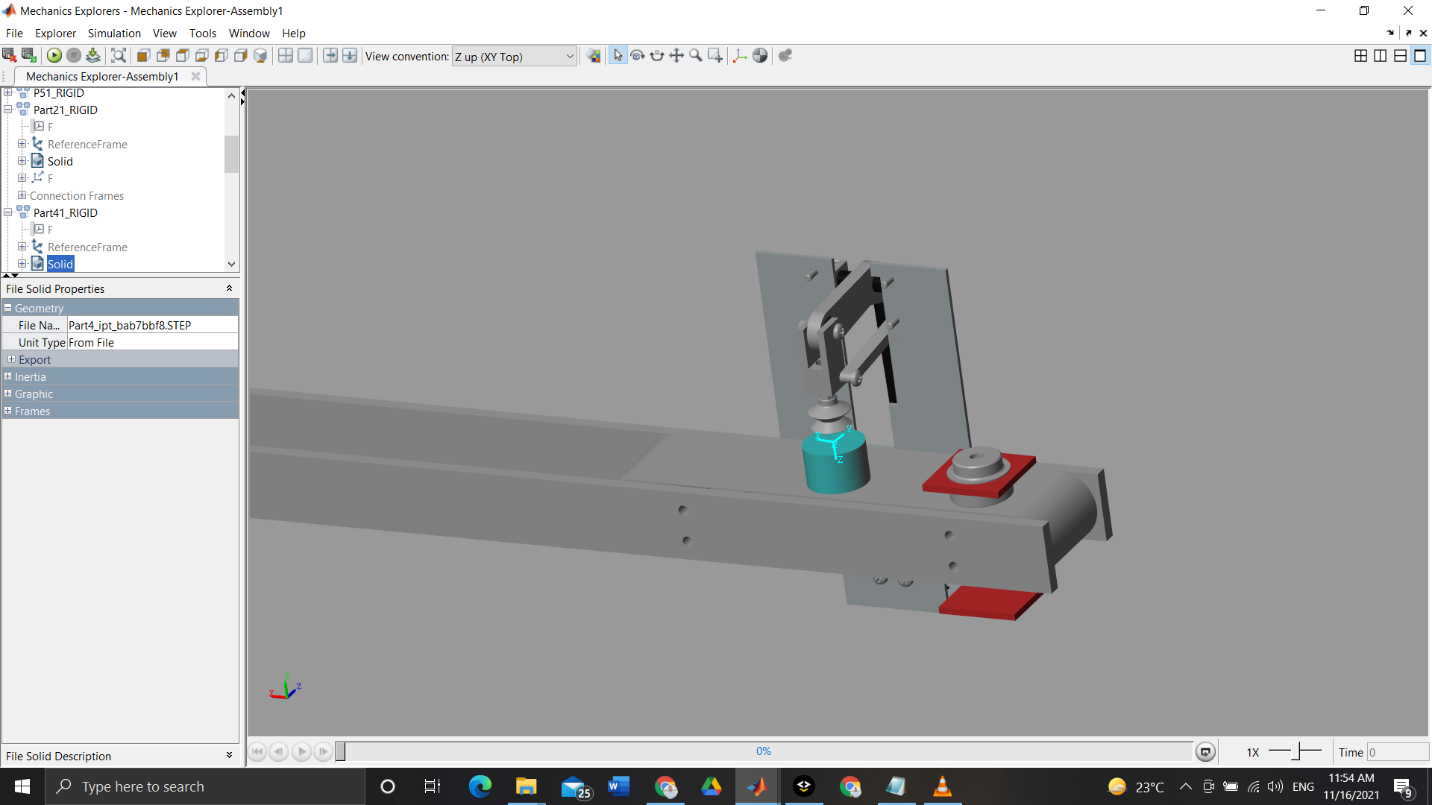
# The Contacts:



First part with the conveyer



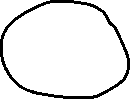
Second part with the conveyer



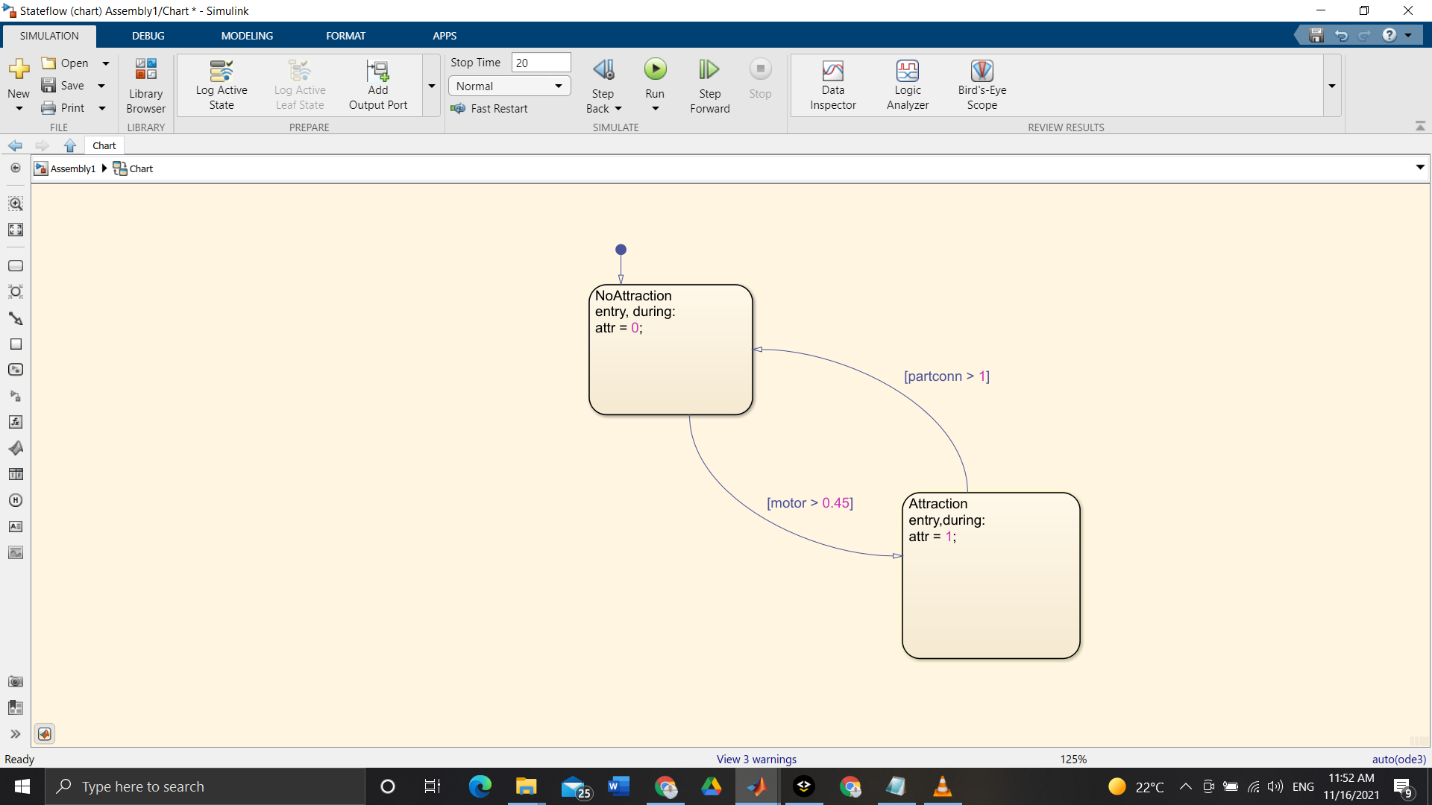
The 2 parts together with face to plane.

Graphical user interface, application

Description automatically generated

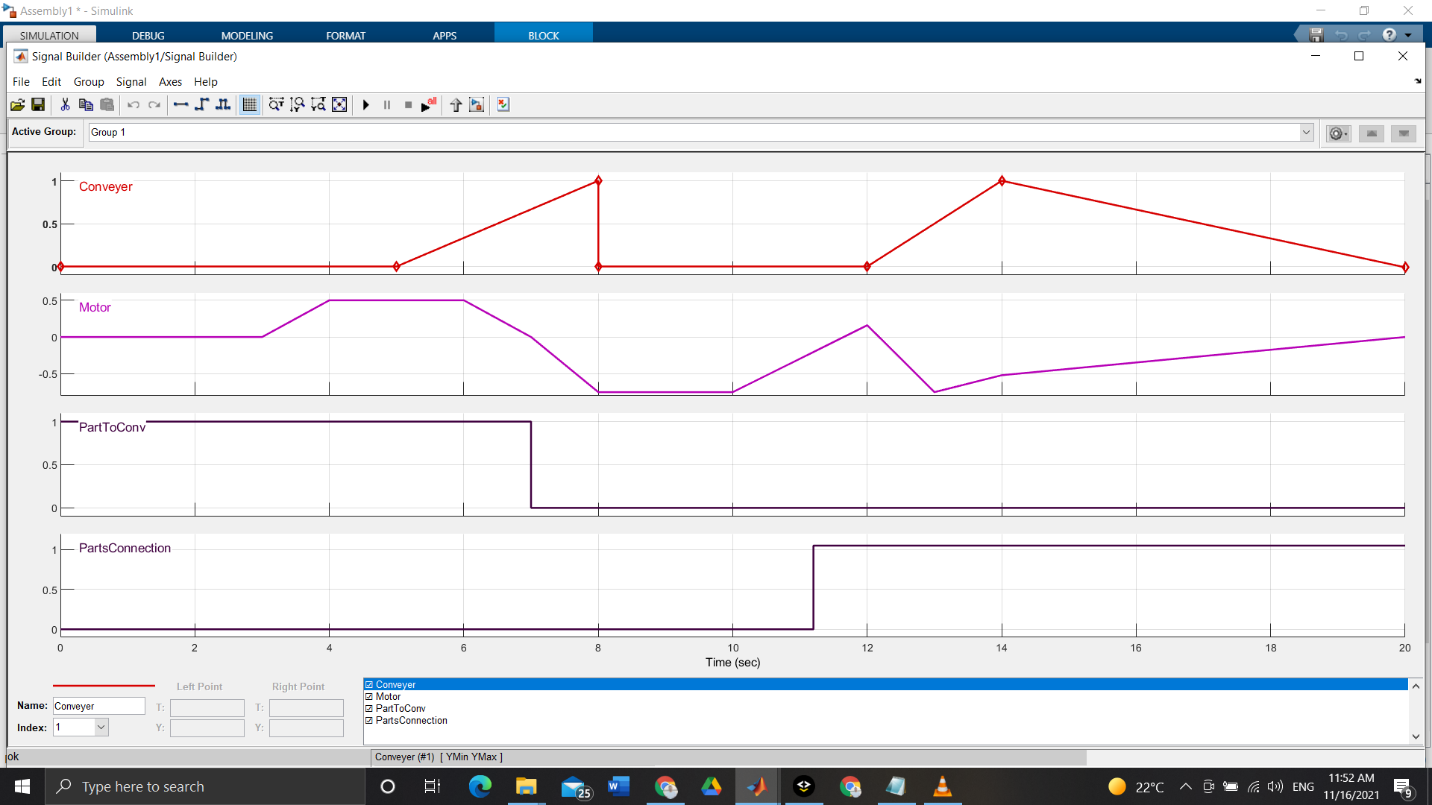


The suction cup attraction to the first part and control by state flow.

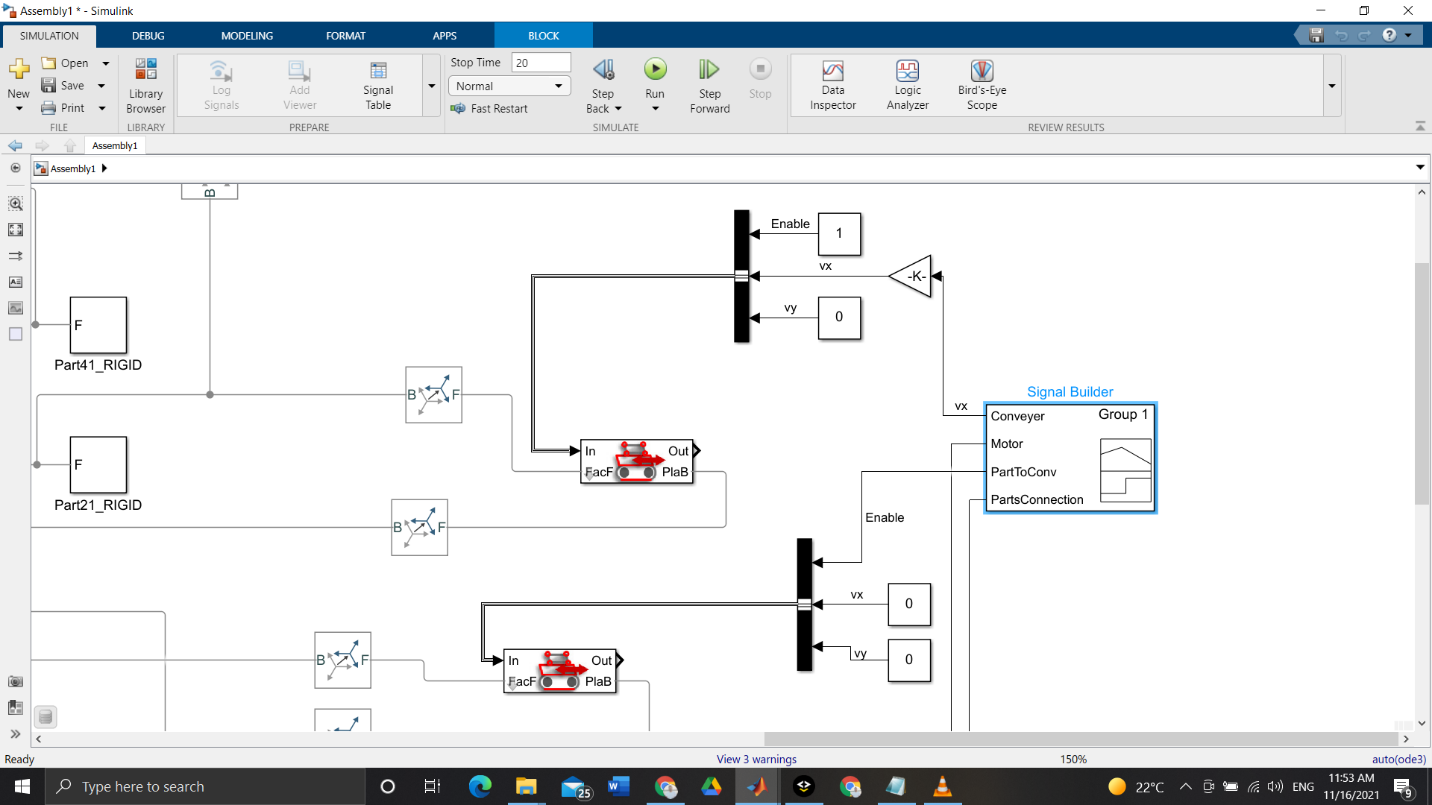


The state flow controlling the suction cup. 2 inputs: motor signal and parts connection.

# The Signals:



4 signals controlling: conveyer, motor, and the second part to conveyer time to be off after the part held up with the suction cup, and the last one to tell that the 2 parts are connected and disengage the suction cup and the part.



Connection of the signal converter and the face to belt to control it, the upper one are always enabled but the second one is for the part being held up with the suction cup, so it unenabled after the part is held up.